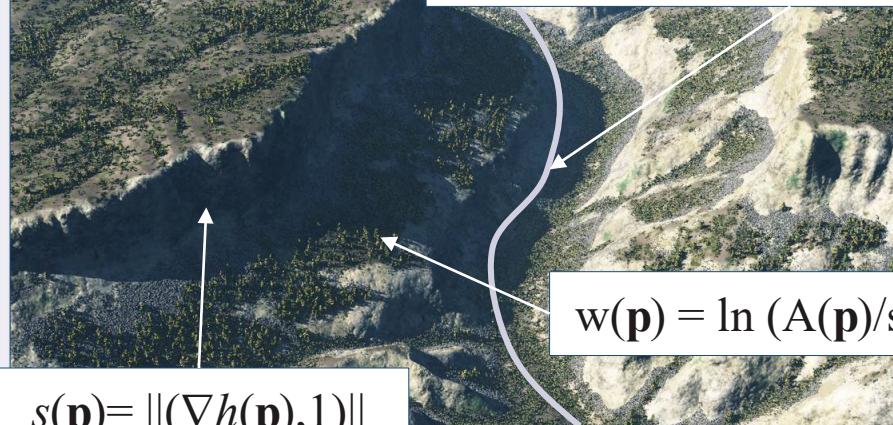


Digital World Modeling

From mathematics ...

$$C(\rho) = \int_0^1 c(\mathbf{p}(x), \dot{\mathbf{p}}(x), \ddot{\mathbf{p}}(x)) dx$$



$$w(\mathbf{p}) = \ln (A(\mathbf{p})/s(\mathbf{p}))$$

$$s(\mathbf{p}) = \|(\nabla h(\mathbf{p}), 1)\|$$

... to the screen

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Digital World Modeling

Data Structures

Procedural Modeling

Erosion Simulation

Procedural Road Generation

Vegetation and Ecosystems

Growth models

Aging and weathering

Synthesis from example

Patch matching

From example

Procedural

Local primitives

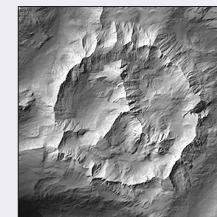
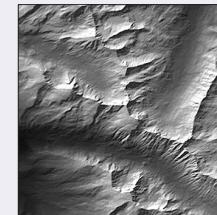
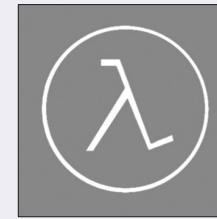
Implicit modeling

Appendix

Création

Recherche et combinaison de motifs [Zhou2007]

Similaire aux méthodes de synthèse de texture



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<http://liris.cnrs.fr/~egalin>

H. Zhou, J. Sun, G. Turk, J. Rehg. Terrain Synthesis from Digital Elevation Models, *IEEE Transactions on Visualization and Computer Graphics*, 13 (4), 834-848, 2007

Procedural Modeling of Height Fields

Faulting

From example

Procedural

Local primitives

Implicit modeling

Appendix

Algorithm

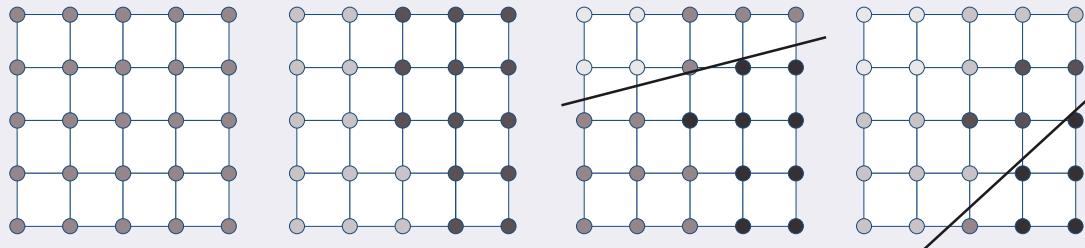
Generate set of faults F_i

Depth is a function of the distance $d(\mathbf{p}, F_i)$

$$h(\mathbf{p}) = \sum_{k=0}^n \delta_i(\mathbf{p})$$

$$\delta_i(\mathbf{p}) = 1 - 2(1 - d(\mathbf{p}, F_i)^2/r^2)^2$$

Distance to lines $d(\mathbf{p}, \Delta_i)$
or circles $d(\mathbf{p}, C)$



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<http://liris.cnrs.fr/~egalin>

B. Mandelbrot. The Fractal Geometry of Nature. 1982.
R. Voss. Random fractal forgeries. *Fundamental Algorithms for Computer Graphics*, 17, 1991.

Recursive subdivision

From example

Procedural

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Appendix

Diamond Square

Height map of size $2^n + 1$

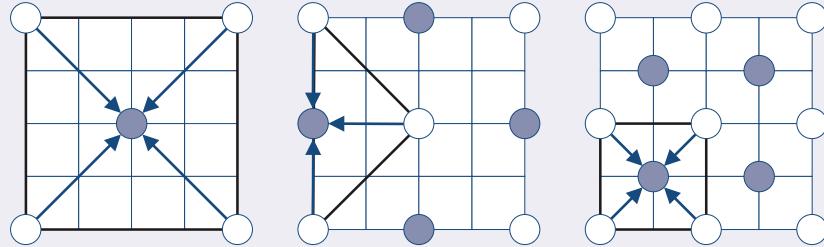
Requires explicit **storage**

```
// Initialise les valeurs aux coins
z[0][0] = z[0][n-1] = z[n-1][0] = z[n-1][n-1] = SEED;

double h = 200.0;
// Itération sur les niveaux, k = taille d'un carré
for (int k = n-1; k >= 2; k /= 2, h /= 2.0)
{
    int l = k/2; // Demi coté

    // Génération pour les carrés
    for (int x=0; x<n-1; x+=k)
    {
        for (int y=0; y<n-1; y+=k)
        {
            double a = (z[x][y] + z[x+k][y] +
                        z[x][y+k] + z[x+k][y+k])/4.0;

            z[x+l][y+l] = a + random(-h,h);
        }
    }
}
```



```
// Génération pour les losanges
for (int x=0; x<n-1; x+=l)
{
    for (int y=(x+l)%k; y<n-1; y+=k)
    {
        double a = (z[(x-l+n)%n][y] +
                    z[(x+l)%n][y] + z[x][(y+l)%n] +
                    z[x][(y-l+n)%n])/4.0;

        z[x][y] = a+random(-h,h);

        // Cas spécial pour les arêtes
        if (x == 0) z[n-1][y] = a;
        if (y == 0) z[x][n-1] = a;
    }
}
```



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J. Lewis. Generalized stochastic subdivision. *ACM Transactions on Graphics*. 6(3), 167–190, 1987.

Global basis functions

From example

Procedural

Local primitives

Implicit modeling

Appendix

Trigonometric functions

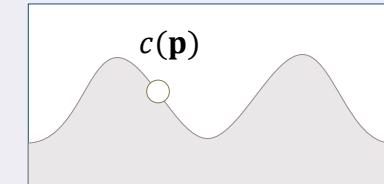
Base sine or cosine $\mathbf{R}^2 \rightarrow [-1,1]$

Scaled cosine c characterized by amplitude and wavelength

$$c(\mathbf{p}) = a \cos(\mathbf{p}/\lambda)$$

Amplitude

Wavelength



Noise

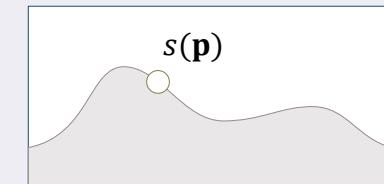
Base noise functions $n: \mathbf{R}^2 \rightarrow [-1,1]$

Scaled noise characterized by amplitude and wavelength

$$s(\mathbf{p}) = a n(\mathbf{p}/\lambda)$$

Amplitude

Wavelength



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Ebert et al. Texturing and Modeling: A Procedural Approach. Academic Press Professional, 1998.

Other basis functions

From example

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Appendix

Modified noise functions

Basis function enhanced to generate ridges

$$r(\mathbf{p}) = 2(1 - |\mathbf{n}(\mathbf{p})|) - 1 = 1 - 2|\mathbf{n}(\mathbf{p})|$$

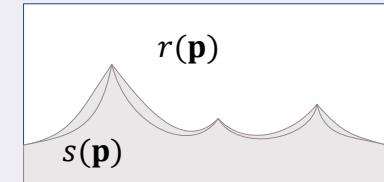
Ridge noise Noise

$$s(\mathbf{p}) = 2(1 - |\mathbf{n}(\mathbf{p})|)^2 - 1$$

Sharpened ridge noise

$$m(\mathbf{p}) = \min_i(\mathbf{n}, \mathbf{n} \circ t_i)$$

Intersection ridge noise t_i is a translation (offset)



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S. Worley. A cellular texture basis function. In Proceedings of SIGGRAPH '96, 291–294, 1996

More complex functions

From example

Procedural

Local primitives

Implicit modeling

Appendix

Fractional Brownian motion

Combination of noise functions $n: \mathbf{R}^2 \rightarrow [-1,1]$ to obtain fractal Brownian motion **fBm**

$$h(\mathbf{p}) = t(\mathbf{p}) = \sum_{k=0}^n a_k n(\mathbf{p}/\lambda_k)$$

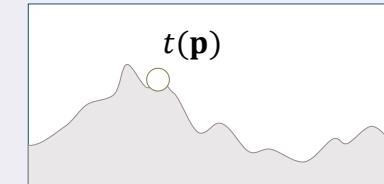
Turbulence

In general, $a_k = a_0 2^{-k}$ and $\lambda_k = \lambda_0 2^{-k}$

Lacunarity [Ebert1998]

Implementation details

Avoid grid artefacts



Transformed point

$$h(\mathbf{p}) = \sum_{k=0}^n a_k n(\mathbf{T}_k(\mathbf{p}) / \lambda_k)$$

$$\mathbf{T}_k(\mathbf{p}) = \mathbf{R}_k \mathbf{p} + \mathbf{o}_k$$

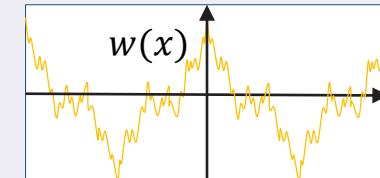
Random offset

Random rotation matrix $\mathbf{R}_k = \mathbf{R}_0^k$

Note

Le value noise n ressemble à la fonction de Weierstrass (1872)
Avec des nombres aléatoires dans $\{-1,1\}$ et une interpolation en cosinus :

$$n \equiv \sum_{i=1}^{\infty} \frac{1}{a^i} \cos(b^i \pi x)$$



Deformations

From example

Procedural

Local primitives

Implicit modeling

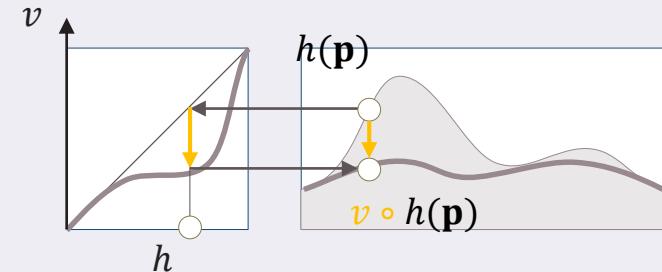
Appendix

Vertical deformations

Any function $v: \mathbf{R} \rightarrow \mathbf{R}$ that modifies the elevation

$$\tilde{h} = v \circ h$$

Deformation applied to the elevation



Horizontal deformations

Any warping $\omega^{-1}: \mathbf{R}^2 \rightarrow \mathbf{R}^2$

$$\tilde{h} = h \circ \omega^{-1}$$

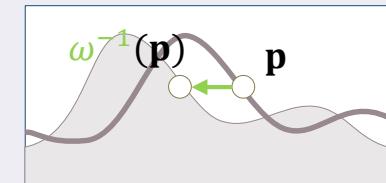
Space deformation applied to the point

$$\omega^{-1}(\mathbf{p}) = \mathbf{p} - \mathbf{t}$$

Translation

$$\omega^{-1}(\mathbf{p}) = \mathbf{p} + n(\mathbf{p})$$

Noise displacement



Fractional Brownian motion

From example

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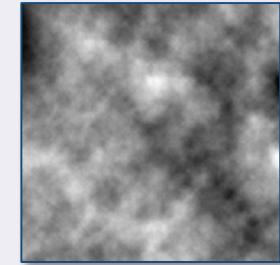
Global function representation

Combination of **noise functions** $n: \mathbf{R}^2 \rightarrow [-1,1]$ to obtain fractal Brownian motion **fBm**

$$h(\mathbf{p}) = t(\mathbf{p}) = \sum_{k=0}^n a_k n(\mathbf{p}/\lambda_k)$$

Turbulence \Leftrightarrow fBm

In general, $a_k = a_0 2^{-k}$ and $\lambda_k = \lambda_0 2^{-k}$



Implementation details

Avoid grid artefacts in the noise n

$$h(\mathbf{p}) = \sum_{k=0}^n a_k n(\mathbf{T}_k(\mathbf{p})/\lambda_k)$$

Transformed point

$\mathbf{R}_k \mathbf{p} + \mathbf{o}_k$

Random offset

Random rotation matrix $\mathbf{R}_k = \mathbf{R}_0^k$



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Challenge: assume the n is Lipschitz with constant λ compute the Lipschitz constant of h

Other basis functions

From example

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Modified noise functions

Basis function enhanced to generate ridges

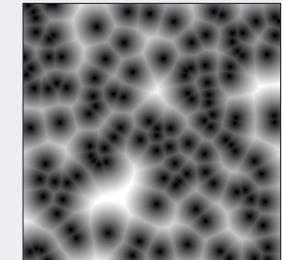
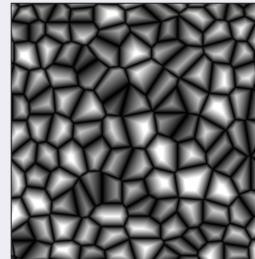
Ridge noise : $r = 2(1 - |n|) - 1 = 1 - 2|n|$

Sharpening operators : $s = 2(1 - |n|)^2 - 1$

Intersection : $m = \min_i(n, n \circ t_i)$ where t_i is a translation (offset)

Other basis functions

Cellular noise [Worley1996] $c: \mathbf{R}^2 \rightarrow [-1,1]$



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S. Worley. A cellular texture basis function. In Proceedings of SIGGRAPH, 291–294, 1996

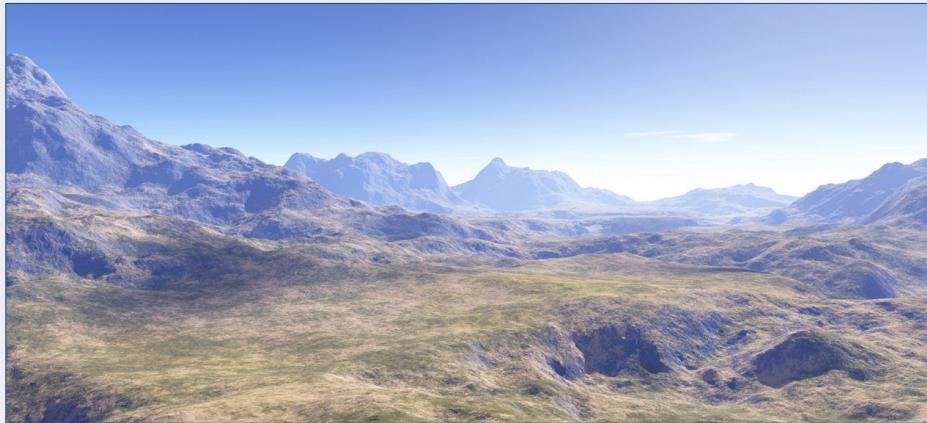
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Procedural Authoring of Height Fields

Construction tree

From example

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Implicit modeling

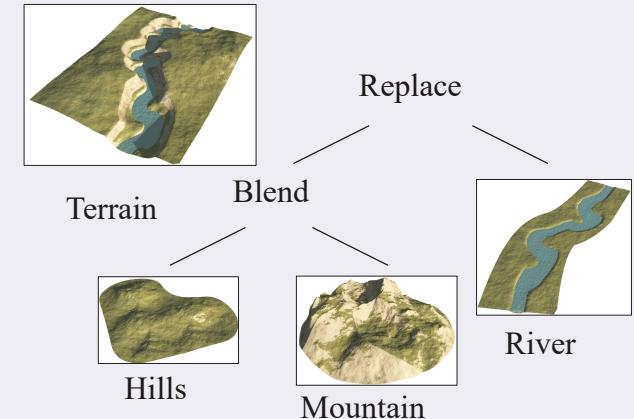
Appendix

Local function representation

Hierarchical representations using primitives organized in a tree

Sparse combination of landforms

Combination of implicit surface properties and elevation functions



Génevaux *et al.* Terrain modeling from feature primitives. *Computer Graphics Forum*, 2015.
Guérin *et al.* Sparse representation of terrains for procedural modeling. *Computer Graphics Forum*, 35, 2, 2016

Fundamentals

From example

Procedural

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Appendix

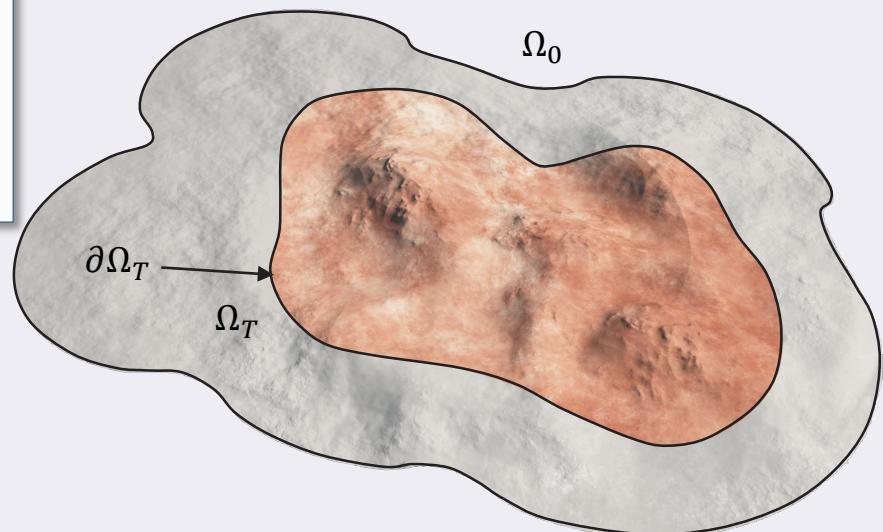
Nodes define two functions

$$\begin{array}{ll} \text{Elevation} & h(\mathbf{p}): \mathbf{R}^2 \rightarrow \mathbf{R} \\ \text{Weight} & \alpha(\mathbf{p}): \mathbf{R}^2 \rightarrow \mathbf{R}^+ \end{array}$$

Support : $\Omega_0 = \{\mathbf{p} \in R^2, \alpha(\mathbf{p}) > 0\}$

Domain : $\Omega_T = \{\mathbf{p} \in R^2, \alpha(\mathbf{p}) > T\}$

C^0 and Lipschitz property



Regions of influence allow for:

- Continuity of the terrain
- Compact support
- Local Lipschitz property



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Control

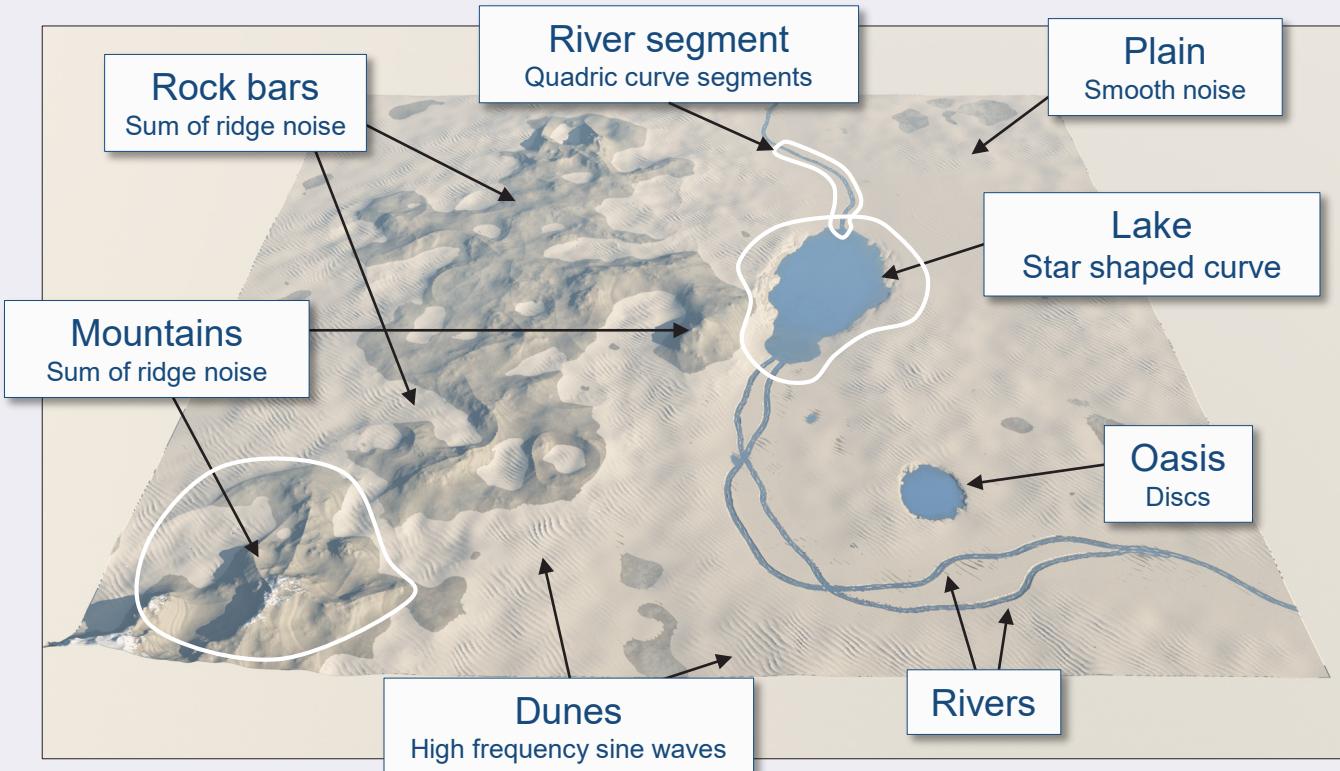
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Disc primitive

From example

Procedural

Local primitives

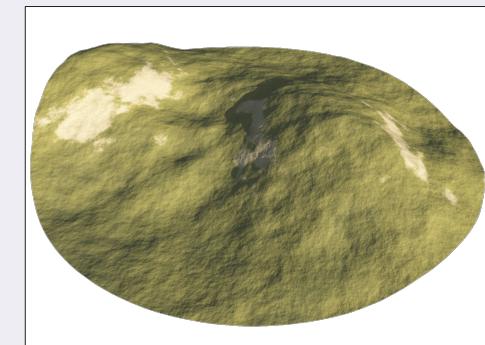
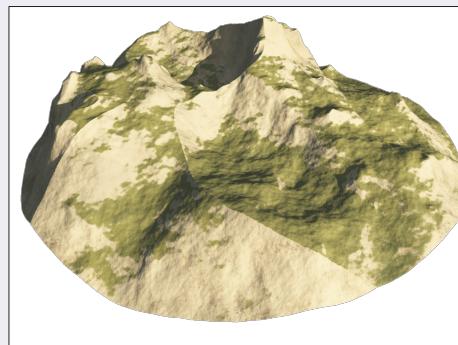
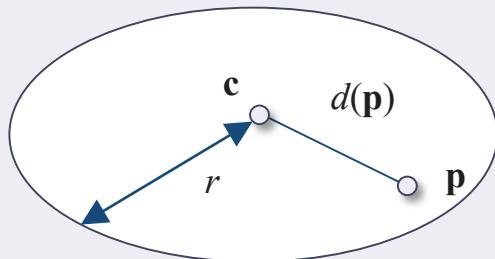
Implicit modeling

Appendix

Mountain and hills over a disc

Elevation $h(\mathbf{p})$ as a combination of noises with amplitude and wavelength

Domain of influence over a disc $\alpha(\mathbf{p}) = g \circ |\mathbf{p} - \mathbf{c}|$



$$g(x) = \left(1 - \frac{x^2}{r^2}\right)^3 \text{ if } x < r \text{ and 0 otherwise}$$

Implementation details

Elevation function

Controls height at center

Precomputed

$$h(\mathbf{p}) = \mathbf{c}_z + t(\mathbf{p}_{xy}) - t(\mathbf{c}_{xy})$$

Turbulence \Leftrightarrow fBm

Curve primitives

From example

Procedural

Local primitives

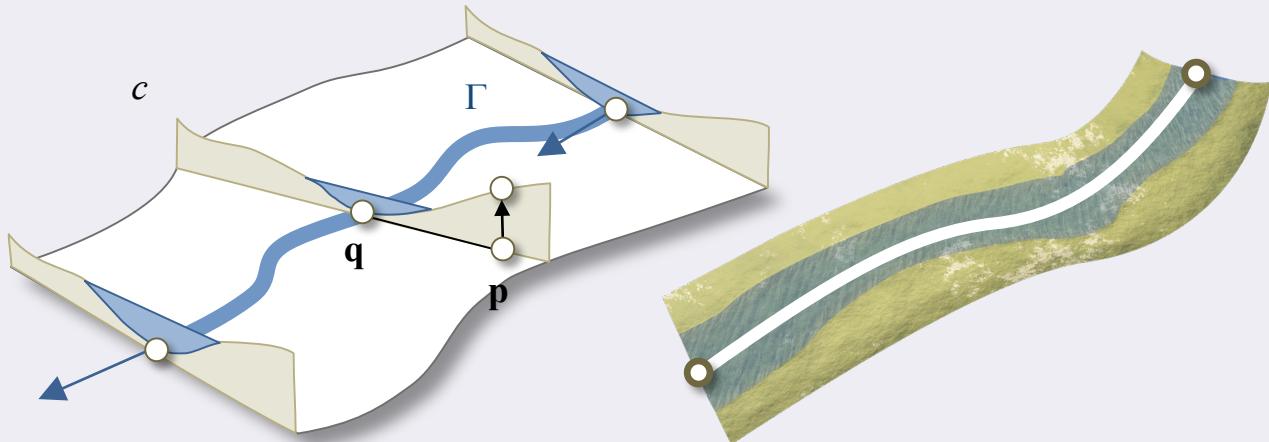
Implicit modeling

Appendix

River segments

Elevation $h(\mathbf{p})$: combination of cross section profile along a curve

Domain of influence around curve $\alpha(\mathbf{p}) = g \circ d(\mathbf{p}, \Gamma)$



Compute the projection $\mathbf{q} = \pi_\Gamma(\mathbf{p})$ of \mathbf{p} on the curve
Elevation is defined as $h(\mathbf{p}) = \mathbf{q}_z + c \circ d(\mathbf{p}, \Gamma)$

Blending

From example

Procedural

Local primitives

Implicit modeling

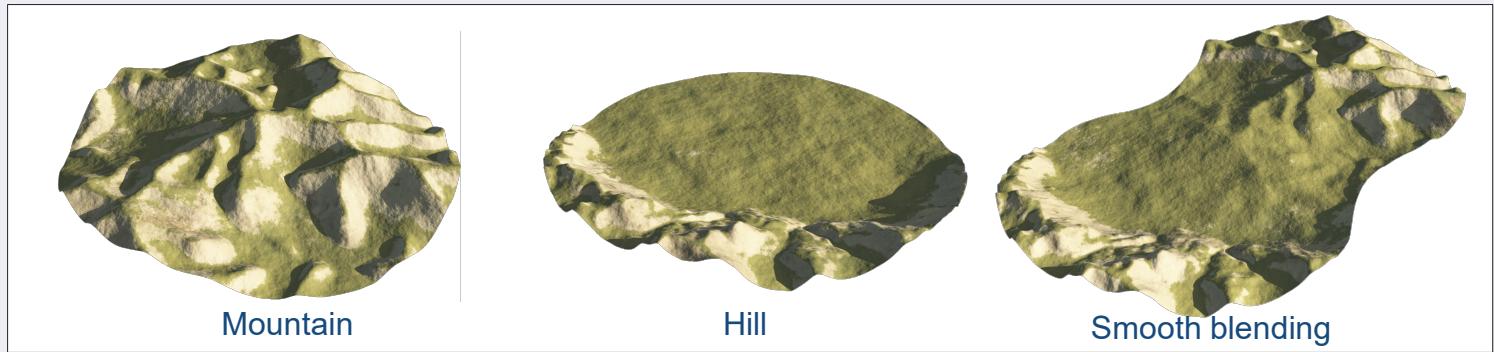
Appendix

Blending two primitives with their own domain

Aggregation of landforms, yields new elevation with new domain

$$\text{Elevation } h = (\alpha_a h_a + \alpha_b h_b) / (\alpha_a + \alpha_b)$$

$$\text{New influence } \alpha = \alpha_a + \alpha_b$$



The contour $\partial\Omega_T$ of the new domain is the contour of the implicit equation $\alpha - T = 0$

$$\partial\Omega_T = \{\mathbf{p} \in R^2, \alpha(\mathbf{p}) = T\}$$

Replacement operator

From example

Procedural

Local primitives

Implicit modeling

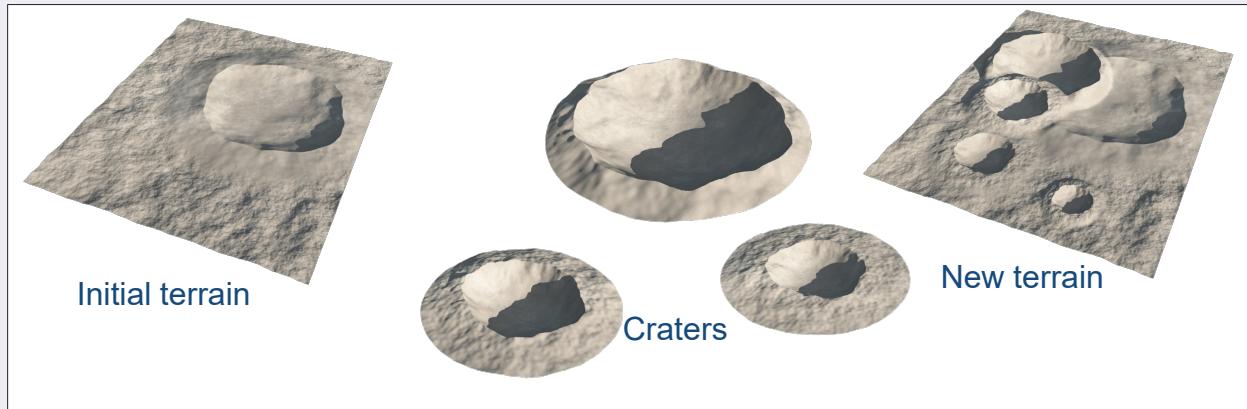
Appendix

Replace a part of a terrain with another one

Asymmetric operator

$$\text{Elevation } h = (1 - \alpha_b)h_a + \alpha_b h_b$$

Preserve influence of the left argument $\alpha = \alpha_a$



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Warping operators

From example

Procedural

Local primitives

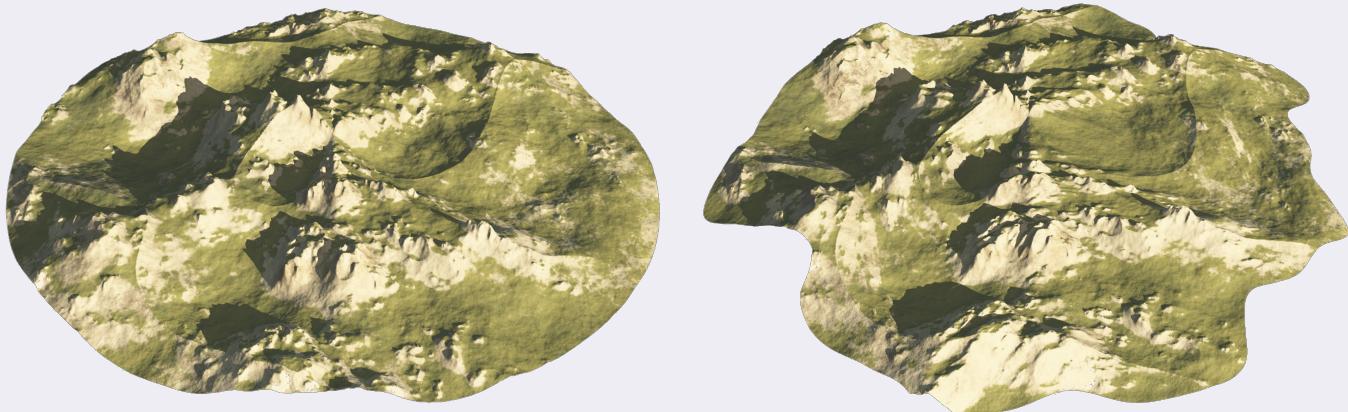
Implicit modeling

Appendix

Deformation of space

Any deformation $\omega^{-1}: \mathbf{R}^2 \rightarrow \mathbf{R}^2$ can be used as warping

Elevation $h = h_a \circ \omega^{-1}$ and coefficient $\alpha = \alpha_a \circ \omega^{-1}$



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Scenery

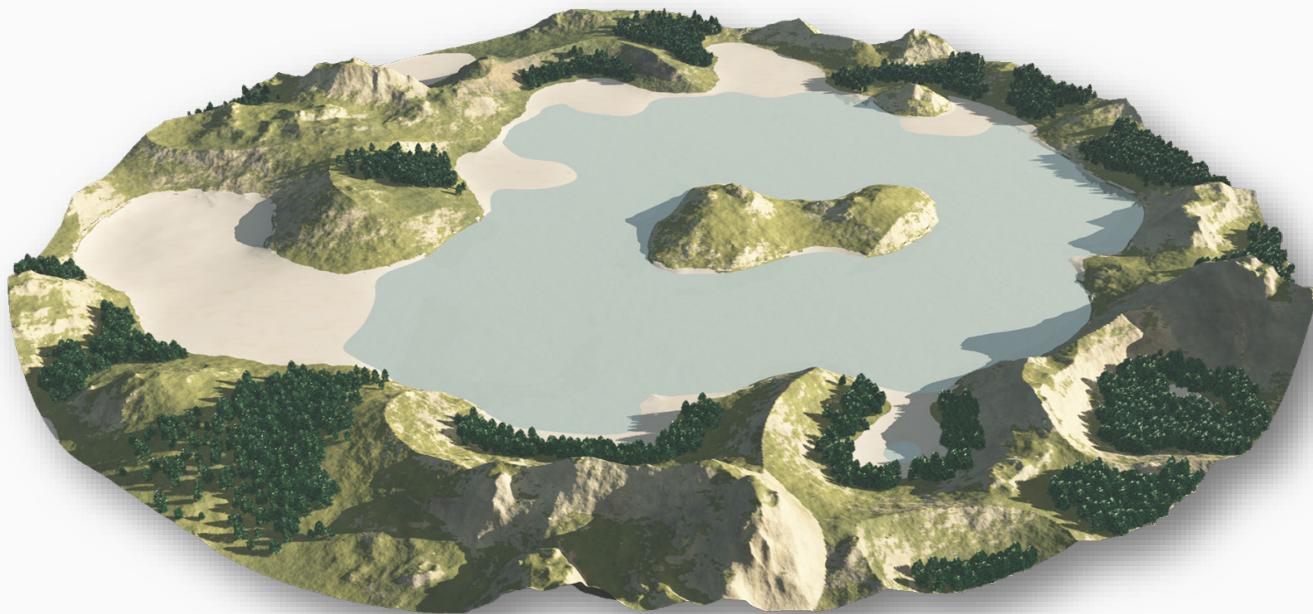
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Scenery

From example

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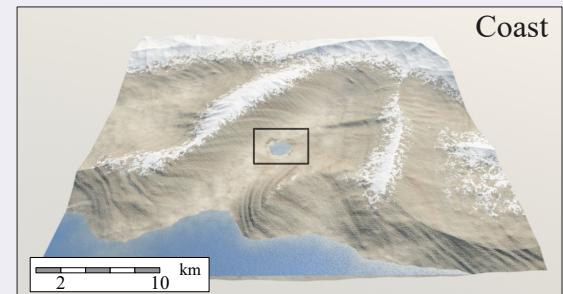
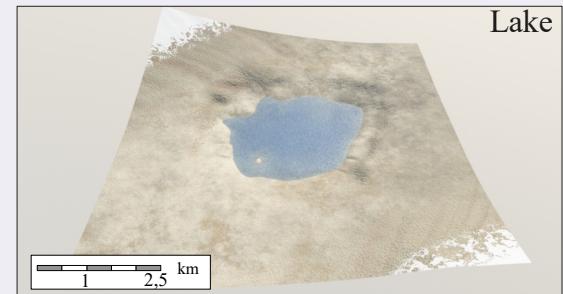
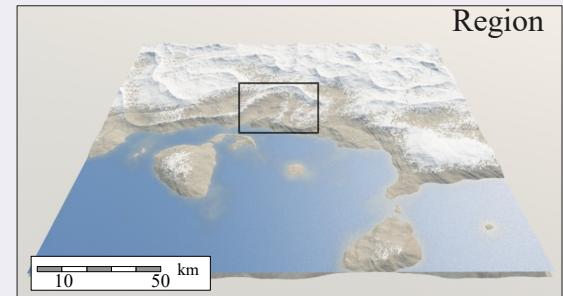
Large scenery

Function representation

200 × 200 km² with specific localized details

Blended primitives authored manually

Tree size **81 kB**



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Procedural Modeling of Volumetric Landforms



Implicit modeling

From example

Procedural

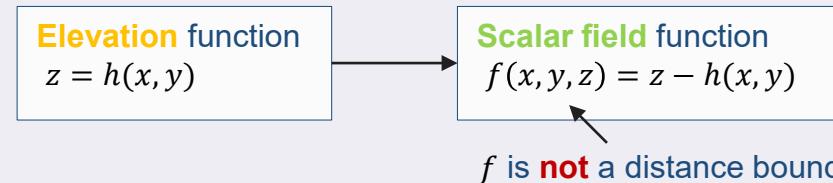
Local primitives

Implicit modeling

Appendix

Implicit surface representation

Elevation functions can be easily converted to an implicit form
Scalar field representation



Distance bound

If f is μ – Lipschitz, then f/μ is a distance bound to the surface [Hart1995]
Fortunately, h is generally λ – Lipschitz, therefore:

$$\mu = \sqrt{1 + \lambda^2}$$

This global bound can be optimized when evaluating along a ray [Galin2020]

The diagram shows the conversion of a scalar field function into a distance bound. A blue-bordered box on the left contains the text "f is a distance bound" and an arrow pointing to a larger blue-bordered box on the right. This right-hand box contains the text "Scalar field function" and the equation $f(x, y, z) = (z - h(x, y))/\mu$.

J. Hart. Sphere Tracing. *The Visual Computer* 12(10), 1995

E. Galin, E. Guérin, A. Paris, A. Peytavie. Segment Tracing Using Local Lipschitz Bounds. *Computer Graphics Forum*, 39(2), 2020.

Construction tree

From example

Procedural

Local primitives

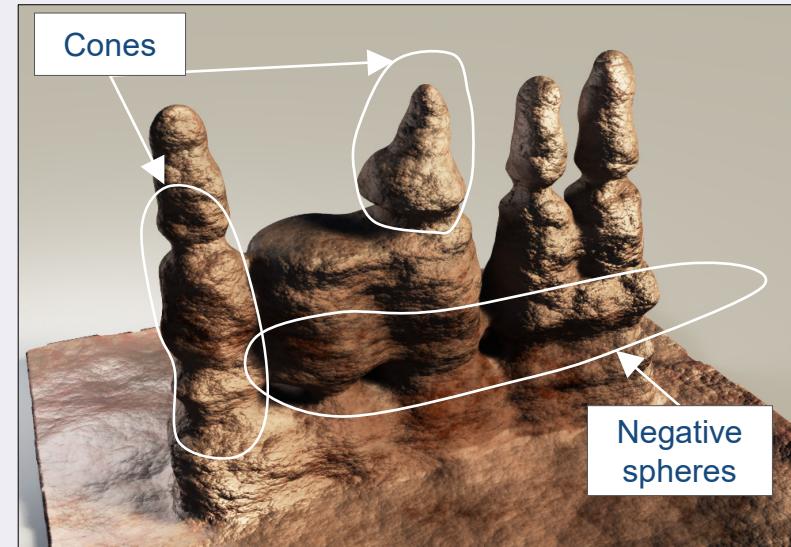
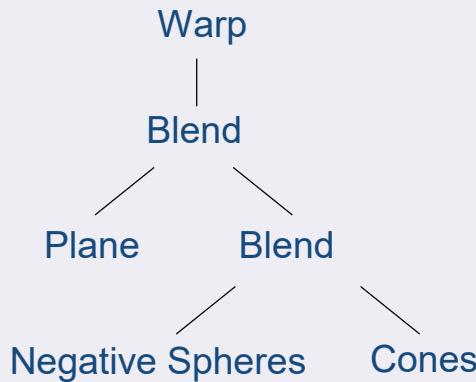
Implicit modeling

Appendix

Scalar field

Volumetric primitives with roughness created from spheres, curves [Paris2019]

Operators : blending, intersection, difference, warping [Wyvill1999]



B. Wyvill, A. Guy, E. Galin, The Blob Tree. *Computer Graphics Forum* 18(2) 1999

A. Paris, E. Galin, A. Peytavie, E. Guérin, J. Gain. Terrain Amplification with Implicit 3D Features. *ACM Transactions on Graphics*, 38(5), 2019

Primitives with details

From example

Procedural

Local primitives

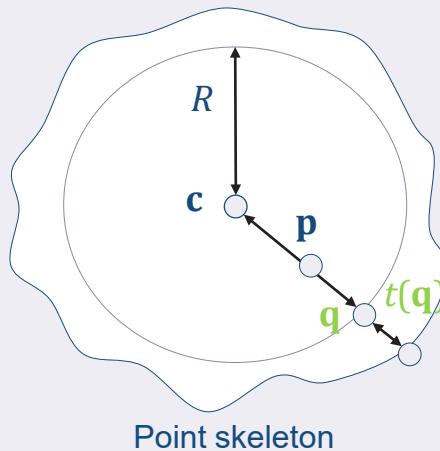
Implicit modeling

Appendix

Roughness

Enhance smooth primitives with noise

Adding noise may cause holes or floating elements



Star shaped primitive

$$\mathbf{q} = c + \frac{\mathbf{p} - c}{\|\mathbf{p} - c\|} + R$$

$$d(\mathbf{p}) = \frac{\|c - \mathbf{p}\|}{R + t(\mathbf{q})}$$

Turbulence



Instantiation

From example

Procedural

Local primitives

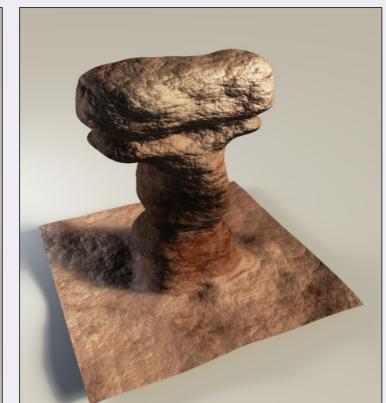
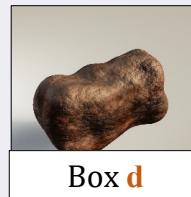
Implicit modeling

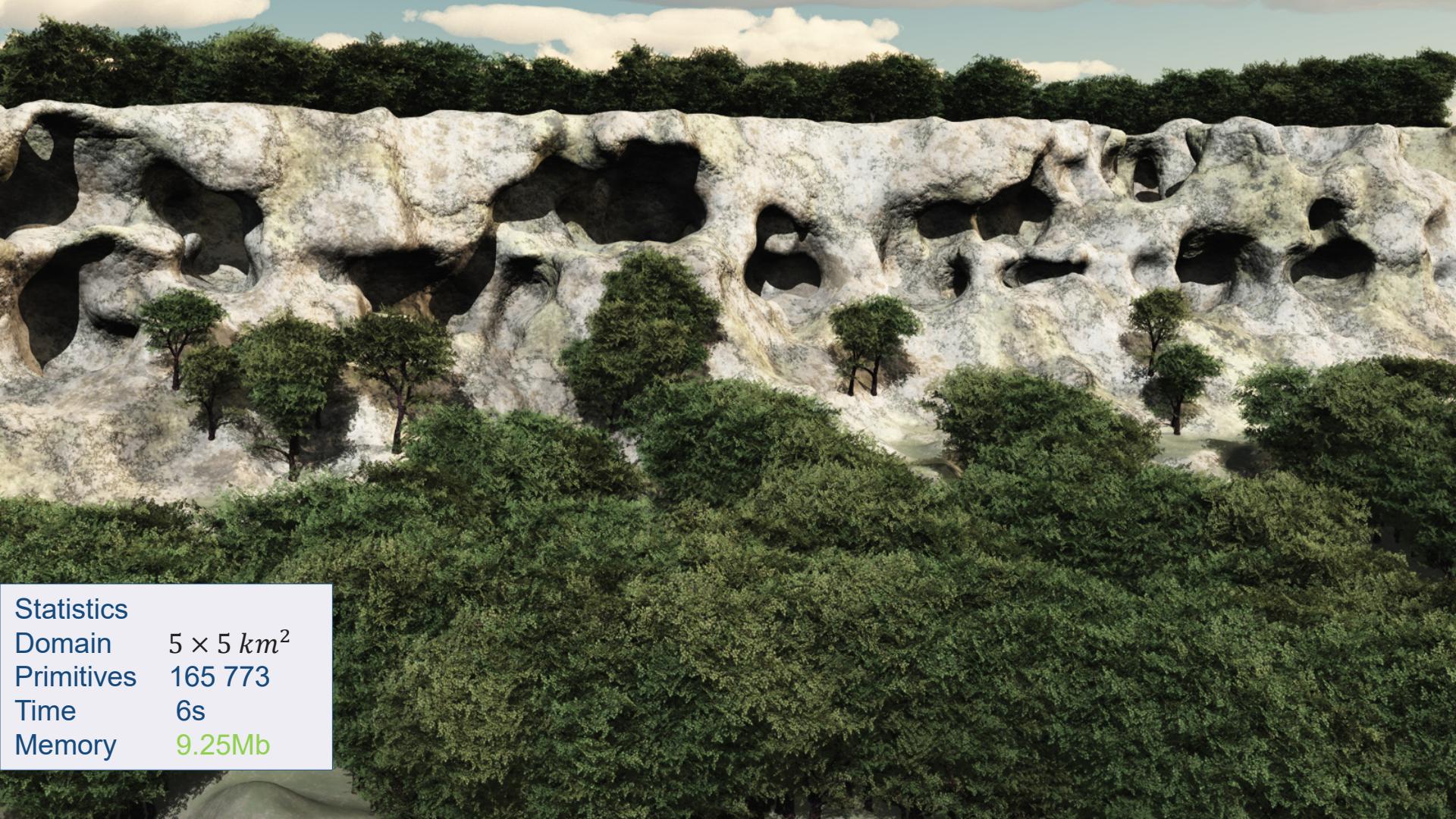
Appendix

Blocks

Aggregate primitives to create an atlas of complex shapes

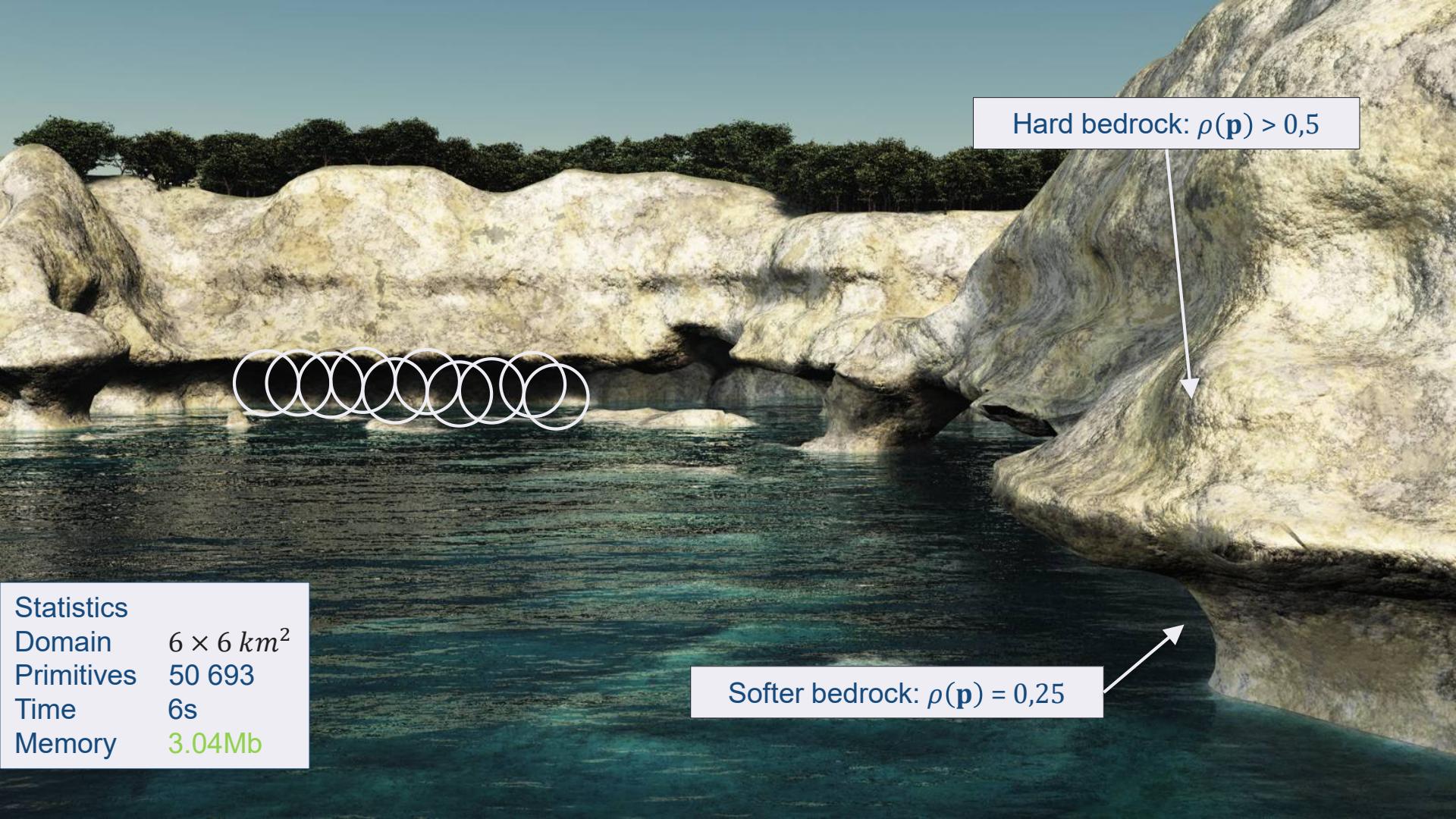
Hierarchically reuse blocks

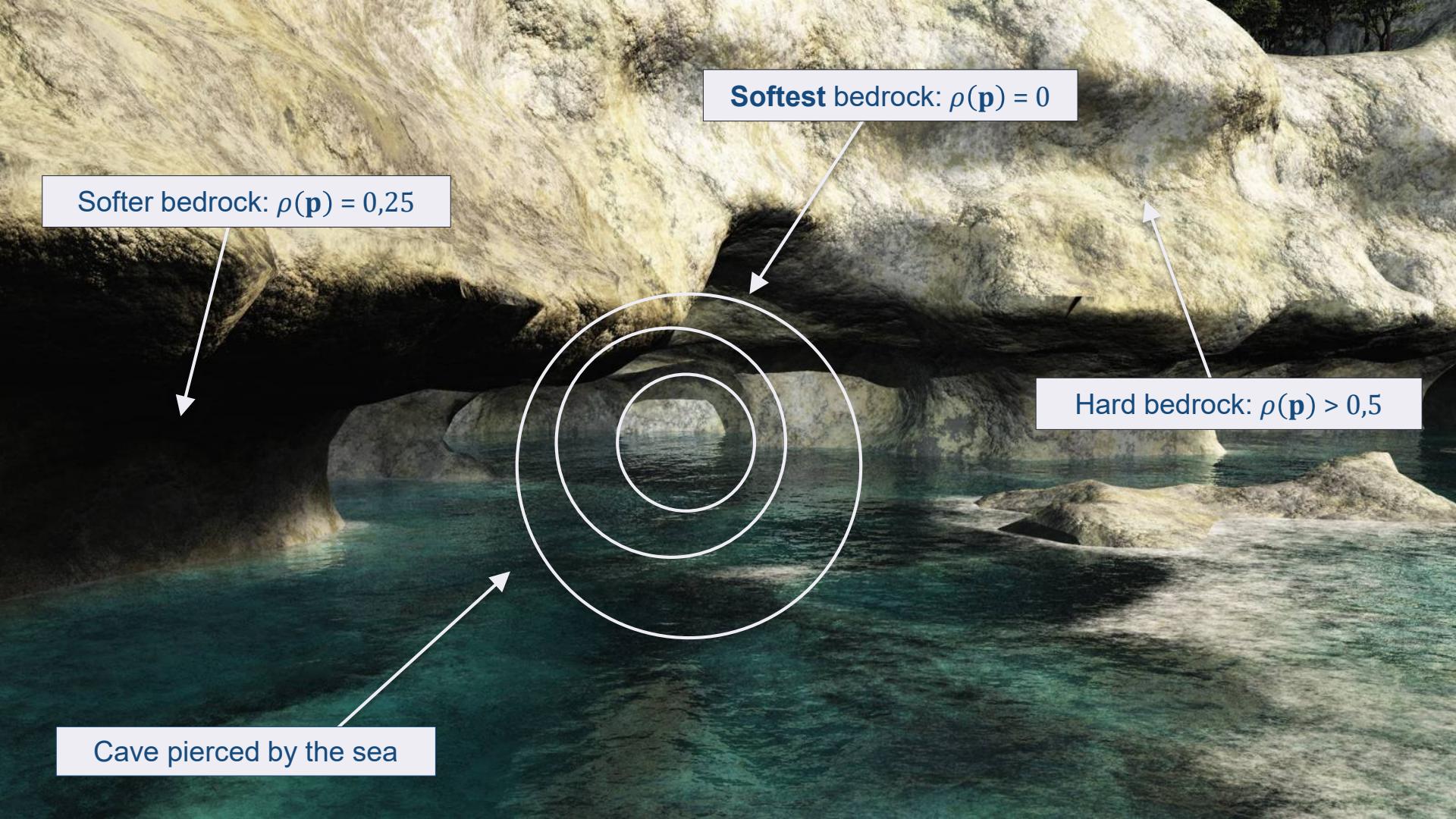




Statistics

Domain	$5 \times 5 \text{ km}^2$
Primitives	165 773
Time	6s
Memory	9.25Mb



A photograph of a coastal scene featuring a large, light-colored rock formation with horizontal sedimentary layers. A sea cave is visible on the left side of the image. The water in the foreground is a clear, teal-green color.

Softest bedrock: $\rho(\mathbf{p}) = 0$

Softer bedrock: $\rho(\mathbf{p}) = 0,25$

Hard bedrock: $\rho(\mathbf{p}) > 0,5$

Cave pierced by the sea

Supplementary material

Conclusion

From example

Procedural

Local primitives

Implicit modeling

Appendix

Height fields and layered height fields
Conspicuous in terrain modeling
Versatile for a variety of generation methods

Function-based models
Useful for modeling some **specific landforms**
Modeling large landscapes with a high resolution



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