

Coalition Games on Interaction Graphs

A horticultural perspective

Nicolas Bousquet, Zhentao Li and Adrian Vetta

EC'15



Outline of this talk

- Coalition games, core and relative cost of stability.
- New graph parameters : vinewidth (and its dual) thicket.
- New bounds on the relative cost of stability.

Coalition games

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- A set I of n agents.
- A superadditive valuation function $v : 2^n \rightarrow \mathbb{N}$. (the money generated by the coalition S if agents of S decide to work on their own project)

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Goal

Distribute money to the agents in such a way, for every coalition S , the money distributed to agents of S is at least $v(S)$.
⇒ No coalition wishes to leave the *grand coalition*.

Definition (core)

The **core** of the coalition game is the **set of payoff vectors** x satisfying the following constraints :

$$\sum_{i \in I} x_i = v(I) \quad \text{The money we can distribute}$$

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- Which conditions ensure that the core is not empty ?
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- Which conditions ensure that the core is not empty ?
- **Relax the definition of core.**

Definition (multiplicative least core)

$$\begin{aligned} \text{Least-Core: } \max \quad & \alpha \\ \text{s.t.} \quad & \sum_{i \in I} x_i = v(I) \\ \text{and} \quad & \sum_{i \in S} x_i \geq \alpha \cdot v(S) \quad \forall S \subseteq I \\ & x_i \geq 0 \end{aligned}$$

Intuition :

Agents of a coalition will leave only if there is a significant benefit in doing so.

Relative Cost of Stability

Another approach :

How much money must be injected by an external authority to stabilize the system ? Expenses / gains.

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$$\begin{aligned} \text{Our gains : } \text{Pack}(\mathcal{G}) &= \max \sum_{S: S \subseteq I} v(S) \cdot y_S \\ \text{s.t.} \quad &\sum_{S \subseteq I: i \in S} y_S \leq 1 \quad \forall i \in I \\ &y_S \in \mathbb{N} \quad \forall S \subseteq I \end{aligned}$$

Since v is supermodular : $\text{Pack}(\mathcal{G}) = v(I)$.

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$y_S \in \mathbb{N} \quad \forall S \subseteq I$

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Our expenses : $Cov(\mathcal{G})^* = \min \sum_{i \in I} x_i$

s.t. $\sum_{i: i \in S} x_i \geq v(S) \quad \forall S \subseteq I$

$x_i \geq 0$

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Remark : This linear program is called the *fractional covering LP*.

* refers to fractional LPs while no * refers to integral ones.

Definition

Definition (Relative Cost of Stability (RCoS))¹

The relative cost of stability of a game \mathcal{G} is the ratio $\frac{Cov^*(\mathcal{G})}{Pack(\mathcal{G})}$.

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Lemma

The Relative Cost of Stability can be **arbitrarily large**.

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Constraints on the coalitions? \Rightarrow Interaction graphs

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Interaction graph

Myerson proposed the following model² : *the agents must be able to communicate if they want to form a viable coalition.*

2. *Conference structures and fair allocation rules*, Myerson (IJGT 1980).

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Definition (interaction graph)

Let H be a graph where :

- Vertices = agents.
- Edges = ability to communicate.

The game \mathcal{G} is on **interaction graph** H if $v(S) > 0 \Rightarrow S$ induces a connected subgraph.

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Examples :

- H is a clique : any coalition may exist.
- H is a stable set : coalitions have size one.

2. *Conference structures and fair allocation rules*, Myerson (IJGT 1980).

Treewidth and coalition game

Theorem (Meir et al.)³

Let H be a graph. The Relative Cost of stability $\frac{Cov^*(\mathcal{G})}{Pack(\mathcal{G})}$ of any coalition game \mathcal{G} on interaction graph H is at most $tw(H) + 1$. Moreover there exist graphs for which this bound is tight.

3. *Bounding the cost of stability in games over interaction networks*, Meir, Zick, Elkind and Rosenschein (AAAI 2013).

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Let H be a graph. The Relative Cost of stability $\frac{\text{Cov}^*(\mathcal{G})}{\text{Pack}(\mathcal{G})}$ of any coalition game \mathcal{G} on interaction graph H is at most $\text{tw}(H) + 1$. Moreover there exist graphs for which this bound is tight.

Actually, they proved the following stronger statement :

Theorem (Meir et al.)

The following inequality holds :⁴

$$\frac{\text{Cov}(\mathcal{G})}{\text{Pack}(\mathcal{G})} \leq_{\forall} \text{tw}(H) + 1$$

$$\begin{aligned} \text{Cov}(\mathcal{G}) &= \min \sum_{i \in I} x_i \quad \text{s.t.} \\ \forall S \subseteq I \quad \sum_{i: i \in S} x_i &\geq v(S) \\ x_i &\in \mathbb{N} \end{aligned}$$

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4. \leq_{\forall} means that every \mathcal{G} on interaction graph H satisfies this inequality.

Informal Result 1

We introduce a new invariant $vw(H)$ that completely characterizes the packing-covering ratio, i.e. for every graph H :⁴

$$vw(H) \leq_{\exists} \frac{Cov(\mathcal{G})}{Pack(\mathcal{G})} \leq_{\forall} vw(H)$$

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Informal Result 2

There exists $\delta > 0$ such that for every graph H , we have

$$vw(H)^{\delta} \leq_{\exists} RCoS(\mathcal{G}) = \frac{Cov^*(\mathcal{G})}{Pack(\mathcal{G})} \leq_{\forall} vw(H)$$

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Informal Result 3

There exists a constant c such that

$$c \cdot vw(H) \leq_{\exists} \frac{\text{Cov}(\mathcal{G})}{\text{Cov}^*(\mathcal{G})} \leq_{\forall} vw(H)$$

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A new graph invariant : vinewidth

A tree T and a function $f : T \rightarrow 2^V$ (the **bag** function) is a tree decomposition of $H = (V, E)$ if :

- For every $v \in V$, the set of nodes containing v in their bags is a *subtree* T_v of T .
- For every edge (u, v) , T_u and T_v intersect .

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The **width** of a vine decomposition is $\max_{t \in T} |f(t)|$.

Definition (vinewidth)

The **vinewidth** $vw(H)$ of H , is the minimum width of a vine-decomposition of H .

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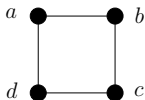
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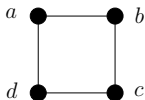
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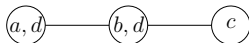
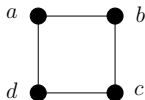
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“Dual” notion : thicket

Definition (thicket)

A collection of subsets of vertices V_1, \dots, V_ℓ is a **thicket** of order k if

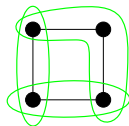
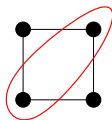
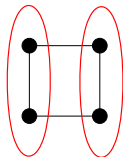
- For every i , the set V_i is *connected*.
- For every $i \neq j$, V_i and V_j *intersect*.
- The minimum number of vertices intersecting all the sets V_1, \dots, V_ℓ is k .

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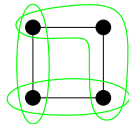
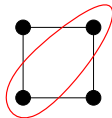
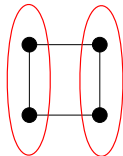


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Structural Theorem (B., Li, Vetta)

The vewidth is equal to the maximum order of a thicket.

Bounds on the Packing-covering ratio

$$\begin{aligned} \text{Cov}(\mathcal{G}) &= \min \sum_{i \in I} x_i & \text{Pack}(\mathcal{G}) &= v(I) \\ \text{s.t.} \quad \sum_{i: i \in S} x_i &\geq v(S) \quad \forall S \subseteq I \\ \text{and} \quad x_i &\in \mathbb{N} \quad \forall i \in I \end{aligned}$$

Theorem (B., Li, Vetta)

For every graph H , we have :

$$vw(H) \leq_{\exists} \frac{\text{Cov}(\mathcal{G})}{\text{Pack}(\mathcal{G})} \leq_{\forall} vw(H)$$

\leq_{\exists} means that there exists a game \mathcal{G} on interaction graph H which satisfies this inequality.

\leq_{\forall} means that every game \mathcal{G} on interaction graph H satisfies this inequality.

Proof of $vw(H) \leq \exists \frac{\text{Cov}(\mathcal{G})}{\text{Pack}(\mathcal{G})}$

Let V_1, \dots, V_ℓ be a thicket of order $vw(H)$.

We consider the following **0 – 1 game** \mathcal{G} where :

- For every i , every connected superset of V_i has value 1.
- The other sets receive value 0.

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Now, we have :

- For every i , the graph induced by V_i is connected : \mathcal{G} is a game on interaction graph H .
- All the sets of a thicket pairwise intersect : the valuation function is **superadditive**.
- In a 0 – 1 game, $Cov(\mathcal{G})$ is the minimum number of agents X such that every coalition contains an agent of X .
 \Rightarrow By definition of the order of the thicket : $Cov(\mathcal{G}) = vw(H)$.

Thus $\frac{Cov(\mathcal{G})}{Pack(\mathcal{G})} = vw(H)$

Bounds on the Relative Cost of Stability

Theorem

There exists $\delta > 0$ such that for every graph H , we have

$$vw(H)^\delta \leq_{\exists} RCoS(\mathcal{G}) = \frac{Cov^*(\mathcal{G})}{Pack(\mathcal{G})} \leq_{\forall} vw(H)$$

δ cannot be improved beyond $\frac{1}{2}$.

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Proof of $RCoS(\mathcal{G}) \leq_{\forall} vw(H)$:

Follows from the previous theorem since

$$RCoS(\mathcal{G}) = \frac{Cov^*(\mathcal{G})}{Pack(\mathcal{G})} \leq \frac{Cov(\mathcal{G})}{Pack(\mathcal{G})} \leq_{\forall} vw(H).$$

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Proof of $vw(H)^\delta \leq_{\exists} RCoS(\mathcal{G})$:

- We can prove that the gap is linear for grids.
- Use the polynomial grid minor theorem.⁵

5. *Polynomial bounds for the grid-minor theorem*, Chekury, Chuzhoy, STOC'14.

Conclusion

Further work :

- Other applications of the vinewidth / thicket duality?
- What is the best coefficient δ ? (δ cannot be improved beyond $\frac{1}{2}$)
- Equivalence between the coefficient of the RCoS and of the grid minor theorem?

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Thanks for your attention !