Independent Set Reconfiguration Which price for locality?

**Nicolas Bousquet** 

joint works with Valentin Bartier, Marthe Bonamy, Clément Dallard, Kyle Lomer, Amer Mouawad

CoRE 2021 - July 2021





## Reconfiguration

A one-player game is a puzzle : one player makes a series of moves, trying to accomplish some goal.



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Giving my current position, can I reach a fixed target position?

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• Applications to random sampling, bioinformatics, discrete geometry...etc...

## Main questions

- **Reachability problem.** Given two configurations, is it possible to transform the one into the other?
- **Connectivity problem.** Given any pair of configurations, is it possible to transform the one into the other?
- **Minimization.** Given two configurations, what is the length of a shortest sequence?

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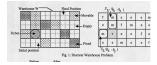
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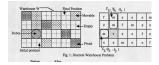
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**Today** : Reachability + Independent Set Reconfiguration.

- [Hopcroft, Schwartz, Sharir '83] Warehouseman's problem -Motion of rectangular robots in a grid.
   ⇒ PSPACE complete (but they need large robots)
  - $\Rightarrow$  PSPACE-complete (but they need large robots).

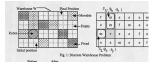


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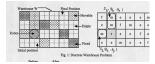
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Theorem (Hearn, Demaine '05) Warehouseman's problem is PSPACE-complete for dominos shaped-robots.

## What about other applications?

#### For puzzles :

 $\rightarrow$  The transformation is local.

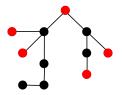
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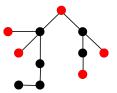
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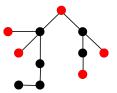
- Random sampling.
- Enumeration.
- Centralized distribution of tokens.
- $\rightarrow$  No locality needed.





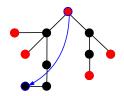
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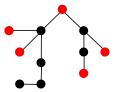
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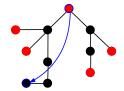
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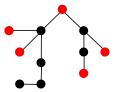
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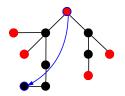
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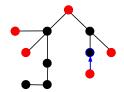
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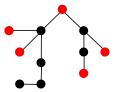


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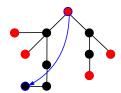
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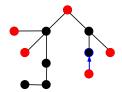
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Question : What is the complexity of TS / TJ-REACHABILITY?

# TS (resp. TJ) REACHABILITY

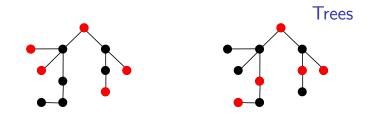
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Input : A graph G, two independent sets I, J.
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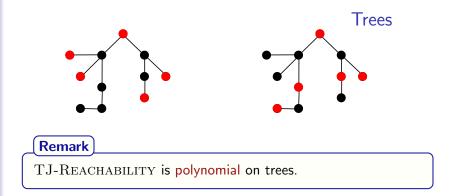
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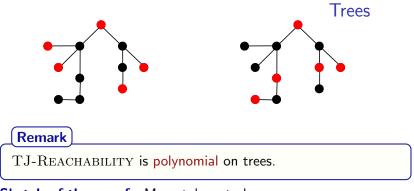
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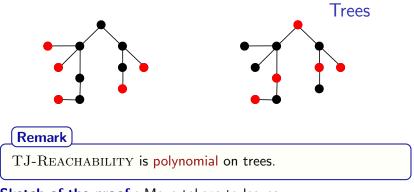
Theorem (Hearn, Demaine '04)

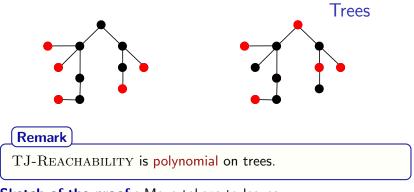
 $\mathrm{TS}/\mathrm{TJ}\text{-}\mathrm{REACHABILITY}$  is PSPACE-complete.

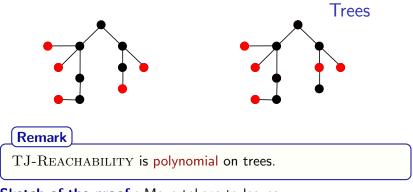


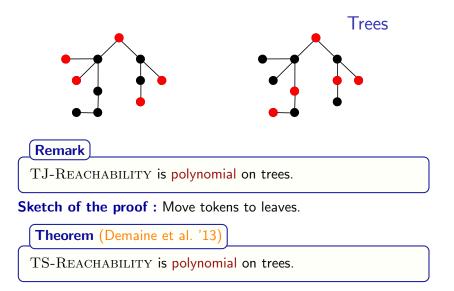


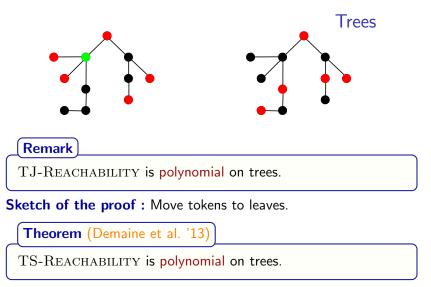






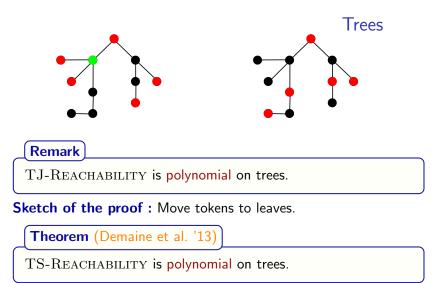






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- YES iff same number of vertices in each component of  $T \setminus X$ .

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## What about TS?

• [Belmonte et al. '19] PSPACE-complete for split graphs.

(split graph =  $V = V_1 \cup V_2$  where  $V_1$  induces a clique and  $V_2$  a stable set)

• [Bonamy, B. '18] Polynomial for interval graphs.

# Bounded treewidth graphs (and below)

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• Small *c* for which ISR is PSPACE-complete on graphs of treewidth at most *c* ?

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### **Questions** :

- Small *c* for which ISR is PSPACE-complete on graphs of treewidth at most *c* ?
- Graphs of treewidth at most 2? Outerplanar? Series-parallel graphs?

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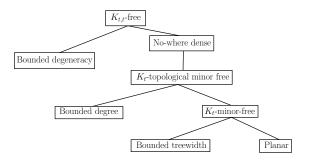
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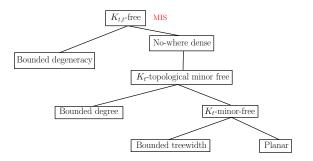
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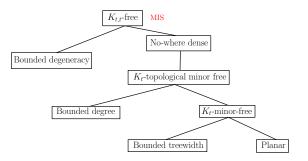
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[Bodlaender, Groenland, Swennenhuis '21+] XL-complete

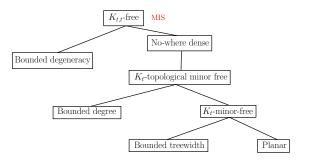






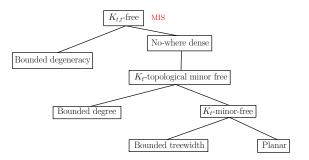
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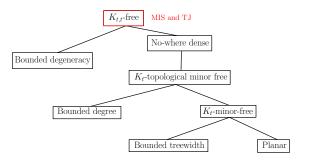
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- [B., Mary, Parreau '18] K<sub>t,t</sub>-free graphs.





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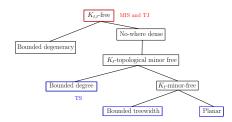
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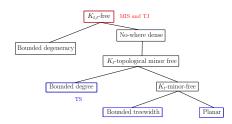
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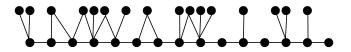
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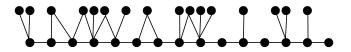




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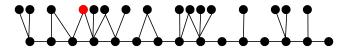




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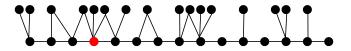




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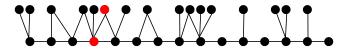




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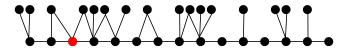




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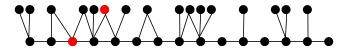




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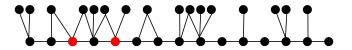




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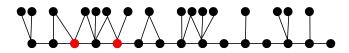


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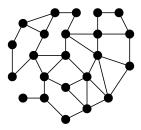
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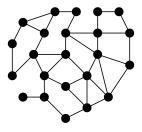
If G admits a long enough geodesic path P with no token on it nor its neighborhood, then P can be collapsed into a single black hole vertex.



#### **Consequences :**

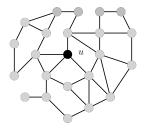
- FPT on bounded degree graphs.
- FPT on planar graphs.





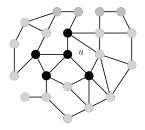
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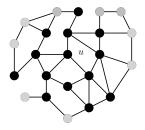
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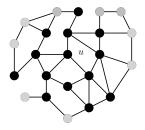
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What is the complexity? Number of rounds.

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 $\rightarrow$  Distributed Reconfiguration of Maximal Independent Sets, Censor-Hillel and Rabie (2019).

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## Thanks for your attention !